

Numerical Methods for PDEs

Stability of the θ -Method and Extensions

(Lecture 7, Week 3)

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- 1 Stability of the θ -method
- 2 Matrix form of the θ -method

von Neumann analysis

For $r = k/h^2$, the θ -method reads

$$\begin{aligned} -\theta r w_{m-1}^{n+1} + (1 + 2\theta r) w_m^{n+1} - \theta r w_{m+1}^{n+1} \\ = (1 - \theta) r w_{m-1}^n + (1 - 2(1 - \theta)r) w_m^n + (1 - \theta) r w_{m+1}^n. \end{aligned}$$

Then, substitute $w_m^n = \xi^n e^{im\omega}$ and simplify

$$\begin{aligned} -\theta r e^{i(m-1)\omega} \xi^{n+1} + (1 + 2\theta r) e^{im\omega} \xi^{n+1} - \theta r e^{i(m+1)\omega} \xi^{n+1} = \\ (1 - \theta) r e^{i(m-1)\omega} \xi^n + (1 - 2(1 - \theta)r) e^{im\omega} \xi^n + (1 - \theta) r e^{i(m+1)\omega} \xi^n \end{aligned}$$

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Using

$$e^{i\omega} - 2 + e^{-i\omega} = -2(1 - \cos(\omega)) = -4 \sin^2(\omega/2)$$

in the above equation gives

$$\xi + 4\xi\theta \sin^2(\omega/2)r = 1 - 4(1 - \theta)r \sin^2(\omega/2)$$

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We need $|\xi| \leq 1$ for stability for all $\omega \in [-\pi, \pi]$. Since ξ is clearly real in this case this means we require $-1 \leq \xi \leq 1$. Now

$$\xi = \frac{1 + 4\theta r \sin^2(\omega/2) - 4r \sin^2(\omega/2)}{1 + 4\theta r \sin^2(\omega/2)} = 1 - \frac{4r \sin^2(\omega/2)}{1 + 4\theta r \sin^2(\omega/2)}$$

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It leaves to consider the case $\xi \geq -1$. This is (on multiplying through by the denominator)

$$\begin{aligned} -1 - 4\theta r \sin^2(\omega/2) &\leq 1 - 4(1 - \theta)r \sin^2(\omega/2) \\ \Rightarrow 2(1 - 2\theta)r \sin^2(\omega/2) &\leq 1 \end{aligned}$$

- (i) If $\theta \geq 1/2$, this last inequality will clearly hold for *all* r .
- (ii) If $\theta < 1/2$, we need in the worst case ($\omega = \pi$) that

$$r \leq \frac{1}{2(1 - 2\theta)}.$$

for stability.

Remark. If $\theta = 0$, we recover the familiar $r \leq 1/2$ result for the FTCS scheme.

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Stability result for the θ -scheme

Summary: The θ -scheme is stable

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Matrix form of the θ -method

We can write the θ -method in much the same form as the BTCS scheme,

$$S\mathbf{w}^{n+1} = M\mathbf{w}^n + (1 - \theta)\mathbf{b}^n + \theta\mathbf{b}^{n+1}$$

where

$$S = \begin{pmatrix} 1 + 2\theta r & -\theta r & 0 & \dots & \\ -\theta r & 1 + 2\theta r & -\theta r & 0 & \dots \\ 0 & -\theta r & 1 + 2\theta r & -\theta r & 0 \\ \dots & \dots & \dots & \dots & \dots \\ & \dots & 0 & -\theta r & 1 + 2\theta r \end{pmatrix},$$

$$\mathbf{w}^n = \begin{pmatrix} w_1^n \\ w_2^n \\ \vdots \\ \vdots \\ w_{J-1}^n \end{pmatrix}, \quad \mathbf{b}^n = \begin{pmatrix} r\alpha(t_n) \\ 0 \\ \vdots \\ 0 \\ r\beta(t_n) \end{pmatrix},$$

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$$M = \begin{pmatrix} 1 - 2(1 - \theta)r & (1 - \theta)r & 0 & \dots & & \\ (1 - \theta)r & 1 - 2(1 - \theta)r & (1 - \theta)r & 0 & \dots & \\ 0 & (1 - \theta)r & 1 - 2(1 - \theta)r & (1 - \theta)r & 0 & \\ \vdots & \vdots & \vdots & \vdots & \vdots & \\ \vdots & \vdots & 0 & (1 - \theta)r & 1 - 2(1 - \theta)r & \end{pmatrix},$$

with corresponding definitions for \mathbf{w}^{n+1} and \mathbf{b}^{n+1} . So supposing we know \mathbf{w}^n , then \mathbf{w}^{n+1} is computed by

- (i) Set $\mathbf{q} = M\mathbf{w}^n + (1 - \theta)\mathbf{b}^n + \theta\mathbf{b}^{n+1}$.
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The matrix S is tridiagonal (if $\theta > 0$), so solving (ii) is fairly quick and easy. This is still more work than solving the explicit FTCS scheme ($\theta = 0$) but not much more.

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Scheme	Order	Type	Stability
$\theta = 0$	$O(k, h^2)$	explicit	$r \leq 1/2$
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(Note the accuracy of some schemes can be increased by choosing a special value for r).

Remark. 1. FTCS scheme easy to apply (because it is explicit), but the time step constraint for stability requires $k \leq 1/2h^2$, such that for h small, we have k very small.

2. The θ -method for $\theta > 1/2$ allows a larger time step for stability (but not too large, otherwise the LTE gets big), and hence can require less overall computing.

3. The Crank-Nicolson scheme ($\theta = 1/2$) has the added advantage of a higher order LTE.

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3. The **Crank-Nicolson scheme** ($\theta = 1/2$) has the added advantage of a **higher order LTE**.

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3. After comparing the θ -method with the FTCS scheme or the Crank-Nicolson scheme with respect to computational costs, which scheme would you recommend at the end?

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